Variational Iteration Method for Solving Boundary Value Problems of Fractional Order

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Abstract

This paper presents an approximate solution of ordinary boundary value problems using the variational iteration method. The fractional derivatives are described in the Caputo sense, because it allows traditional initial and boundary conditions to be included in the formulation of the problem. The solutions of proposed fractional equations are calculated in the form of convergent series with easily computable components. Also, we construct the variational iteration formula and its convergence to the exact solution for solving system of fractional order differential equations. Some examples are solved as an illustration to the method, in order to show the accuracy of the method and comparison with results the exact solution for the given test problems, which are given for comparison purpose. [DOI: 10.22401/ANJS.00.2.09]

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1. Introduction

Variational iteration method (VIM) which was proposed by [He, 2007] and has been recently and intensively studied by several scientists and engineers that is favorably applied to various kinds of linear and nonlinear problems. The method has been shown to solve effectively, easily and accurately a large class of linear and nonlinear problems.

Generally, one or two iterations may lead to high accurate solutions. This method is, in fact, a modification of the general Lagrange multiplier method [He, 2007], [Batiha B., 2008] into an iteration method, which is called correction functional. Generally speaking, the solution procedure of the VIM is very effective, straightforward and convenient. Several studies have been conducted to compare the VIM with other existing techniques, and it is shown by all that this method may give exact solutions faster than other methods, in which the convergence concept has been proved a substantial amount of research work. It is remarkable that the VIM gives rapidly convergent successive approximations of the exact solution if such a solution exists: otherwise, a few approximations can be used

for numerical purposes, [Al-Jamal, 2009]. has been directed to the study of the VIM by many well-known researchers [Guo, 2013], [Momani, 2006].

This paper is organized as follows; in section 2 some basic and fundamental definitions of fractional calculus are presented for completeness purpose. In section 3, we describe the formulation as well as, the convergence of the variational iteration method for solving two-points boundary value problems and then some illustrative examples are given in section 4.

2. Basic Concepts

In this section, basic definitions and fundamental concepts related to this paper will be introduced, including fractional order differentiation and integration in addition to the basic of elements of the VIM.

Definition 1:

Riemann-Liouville definition of fractional integral operator of order $q \ge 0$ [Fang Li, 2012], for a continuous function f is defined as:

^{RL} I^q f (x) =
$$\frac{1}{\Gamma(q)} \int_0^x (t-s)^{q-1} f(s) ds, q > 0, x > 0$$

...(1)

where Γ is the well-known Euler's gamma function, defined by:

 $\Gamma(\mathbf{x}) = \int_0^{\mathbf{x}} e^{-t} t^{\mathbf{x}-1} dt, \mathbf{x} > 0$

Some basic properties that are satisfied by Riemann-Liouville fractional order integration may be summarized for all p, $q \ge 0$ and $\gamma \ge -1$, as follows:

1.
$$^{\text{RL}}I^0 f(x) = f(x).$$

2. ${}^{\text{RL}}I^{q}x^{p} = \frac{\Gamma(p+1)}{\Gamma(q+p+1)}x^{q+p}$...(2) 3. ${}^{\text{RL}}I^{q}I^{p}f(x) = {}^{\text{RL}}I^{p} {}^{\text{RL}}I^{q}f(x) =$

 $^{RL}I^{p+q}f(x).$

Definition 2:

Caputo fractional order derivative of order $q \ge 0$ [Fang Li, 2012], [Murio, 2006] for a continuous function f is defined as follows:

$${}^{C} D^{q} f(x) = \begin{cases} \frac{1}{\Gamma(m-q)} \int_{0}^{x} \frac{f^{(m)}(\tau)}{(x-\tau)^{q+1-m}} d\tau, m-1 < q \le m \\ \\ \frac{d^{(m)}}{dx^{(m)}} f(x), q = m \end{cases}$$

The Caputo fractional order derivative satisfies the following properties:

- 1. $^{C}D^{q} c=0$, where c is a constant.
- 2. ^C $D^q x^p = 0$, for $p \le q 1$, $q, p \in \mathbb{R}^+$.

3. ^C D^q x^p =
$$\frac{\Gamma(p+1)}{\Gamma(p-q+1)}$$
 x^{p-q}, for p>q-1,
q, p $\in \mathbb{R}^+$(4)

- 4. ^C $D^{q} R^{L} I^{q} f(x) = f(x).$
- 5. ${}^{\text{RL}}I^{q\ C}D^{q}f(x) = f(x) \sum_{k=0}^{m-1}f^{(k)}(0^{+})\frac{x^{k}}{k!},$ where $m - 1 < q \le m, m \in \mathbb{N}.$

3. Variational Iteration Method

The basic idea of the VIM [He, 2007], [Elham, A., 2004] is to consider the following general non-linear equation given in operator form:

 $L(y(x)) + N(y(x)) = g(x), x \in [a, b]$...(5) where L is a linear operator, N is a nonlinear operator and g is any given function which is called the non-homogeneous. Now rewrite eq. (5) as follows:

$$L(y(x)) + N(y(x)) - g(x) = 0$$
 ...(6)

and let y_n be the nth approximate solution of eq. (5), then:

$$\begin{split} L(y_n(x)) + N(y_n(x)) - g(x) \neq 0 & \dots(7) \\ \text{the correction functional for eq.(5), is} \\ \text{given by:} \end{split}$$

$$y_{n+1}(x) = y_n(x) + \int_0^x \lambda(s) \{L(y_n(s) + N(\tilde{y}_n(s)) - g(s)\} ds$$
 ...(8)

where λ is the general Lagrange multiplier which can be identified optimally via the variation theory, the subscript n denotes the nth approximation of the solution y and \tilde{y}_n is considered as a restricted variation, i.e., $\delta \tilde{y}_n = 0$, [Batiha, 2008].

To find the $(n + 1)^{th}$ iteration of the solution using the VIM, one must first determine the Lagrange multiplier λ that will be identified optimally via integration by parts. Then the successive approximation $y_n(x)$, n = 0, 1,...; of the solution y(x) will be readily obtained upon using the obtained Lagrange multiplier and by using any selective initial guess function $y_0(x)$.

The approximation of initial solution y_0 may be selected to be any function that just satisfies at least the initial and boundary (3) conditions with λ pre-determined, then several approximations $y_n(x)$, n = 1, 2, ... will follows immediately, and consequently the exact solution may be arrived since one may prove that $y(x) = \lim_{n \to \infty} y_n(x)$. In other words, the correction functional for eq. (8) give several will approximations, and therefore the exact solution is obtained as the limit of the resulting successive approximations.

4. Problem Formulation and the VIM for Solving BVP of Fractional Order

The consider problem of this paper is to solve the following BVP of fractional order: ^c D^q $v(x) = f(x, v(x), {^c}D^p v(x)), 1 < q \leq$

$$Y = I(x, y(x), D \quad y(x)), 1 \leq q \leq 2$$

$$2 \quad 0 \leq n \leq 1 \quad x \in [2, h] \qquad (0)$$

2, 0 ...(9)where f is given continues function and theinitial condition are considered of two-points,as follows:

 $y(a) = y_a, y(b) = y_b$...(10) Now, the formulation of the VIM of

problem (9)-(10) is given in the next theorem:

Theorem 1:

Consider the two-points BVP (9)-(10) of fractional order, then the sequence of iterative solutions using the VIM is given by:

 $y_{n+1}(x) = y_n (x) + {}^{RL} I^q (x - s)$ $[{}^{c} D^q y(s) - f(s, y(s), {}^{c} D^p y(s))] ...(11)$ for all n = 0,1,...**Proof:** Since from eq.(11): ${}^{c} D^q y(x) = f(x, y(x), {}^{c} D^p y(x)), 1 < q \le 2, 0 < p \le 1, x \in [a, b]$ which may be rewritten equivalently as:

 ${}^{c}D^{q}y(x) - f(x, y(x), {}^{c}D^{p}y(x)) = 0$

Therefore, the correction functional using the VIM is given by:

$$y_{n+1}(x) = y_n (x) + {^{RL}I^q} [\lambda(x,s) \{ {^cD^q} y_n(s) - f(s, \tilde{y}_n(s), {^cD^p} y_n(s)) \}] ...(12)$$

and in order to find λ , approximate ^{Re} I^q by a single integral and approximate ^c D^q y by y["], then eq.(12) will be reduced to:

$$y_{n+1}(x) = y_n(x) + \int_a^x [\lambda(x,s) [y_n''(s) - f(s, \tilde{y}_n(s), {}^c D^p y_n(s)] ds ...(13)$$

by taking the first variation of eq.(13) with respect to y_n and taking thus $\delta y_n(a) = \delta y'_n(a) = 0$ yields to:

$$\delta y_{n+1}(x) = \delta y_n(x) + \delta \int_a^x \lambda(x,s) [y_n''(s) - f(s, \tilde{y}_n(s), {}^c D^p y_n(s)] ds$$

where y_n is considered as a restricted variation and hence:

$$\delta y_{n+1}(x) = \delta y_n(x) + \int_a^x \lambda(x,s) \, \delta y_n''(s) ds$$
...(14)

carrying the integration by parts twice, then eq.(14) will be

$$\begin{split} \delta y_{n+1}(x) &= \delta y_n(x) + \lambda \delta y'_n(s)|_a^x - \\ \lambda' \delta y_n(s)|_a^x + \int_a^x \lambda''(x,s) \, \delta y_n(s) ds \\ &= (1 - \lambda') \delta y_n + \lambda \delta y'_n(x) + \\ \int_a^x \lambda''(x,s) \, \delta y_n(s) ds \end{split}$$

and from the theory of calculus of variation, and since δy_n is arbitrary, then the following Euler equation is obtained.

$$\lambda''(\mathbf{x}, \mathbf{s}) = 0$$
 ...(15)
With stationary conditions:

$$1 - \lambda (x, s)|_{s=x} = 0, \lambda (x, s)|_{s=x} = 0...(3.12)(16)$$

Solving (15)-(16) will give the solution $\lambda(x, s) = x - s$

Thus the correction functional will reads as follows

$$y_{n+1}(x) = y_n(x) + {^{RL}I^q[(x-s)]} ({^cD^qy_n(s) - f(s, y(s), {^cD^py(s)})}]. \blacksquare$$

5. Convergence Analysis

In the present section, the convergence of the sequence of approximate iterative solutions of problem(9)-(10) using the VIM for solving two-point boundary value problems of fractional order will be proved (for cases 1 and 3). The main idea of the proof is based upon evaluating the upper bound of the error term between the exact and approximate solution of problem (9)-(10) which is proved to be tends to zero as n tends to ∞ .

Theorem 2:

Let $C^{2}[0,1]$ be the exact and approximate solution of the BVP of fractional order:

^c D^q y(x) = f(x, y(x), ^c D^p y(x)), 1 < q 2, 0 \le 1, x \in [a, b]...(16) and $\|{}^{c} D^{q} y\| \le \|y\|$, if $E_n(x) = y_n(x) - y(x)$ and f satisfies Lipschitz condition with constant L, such that $L < \frac{\Gamma(q)}{1+c}$, then the sequence of approximate solutions $\{y_n\}$, n = 0, 1, ...; converges to the exact solution.

Proof:

Since the VIM is given by: $y_{n+1} = y_n + {}^{RL} I^q \left[(x - s) {}^c D^q y_n - f(s, y_n(s), {}^c D^p y_n(s)) \right] \dots (17)$ and y is the exact solution, hence: $y = y + {}^{RL} I^q \left[(x - s) {}^c D^q y - f(s, y(s), {}^c D^p y(s)) \right] \dots (18)$

subtraction eq.(17) from eq. (18) will yields to:

$$y_{n+1} - y = y_n - y + {}^{RL} I^q [(x - s) \left({}^c D^q y_n - {}^c D^q y - \left(f(s, y_n(s), {}^c D^p y_n(s) \right) - f(s, y(s), {}^c D^p y(s) \right)]$$

i.e.,

$$\begin{split} E_{n+1}(x) &= E_n(x) + {}^{RL} I^q \left[(x-s) (\,{}^c D^q E_n - \\ & \left(f \left(s, y_n(s), \,{}^c D^p y_n(s) - \right. \\ & \left. f \left(s, y(s), \,{}^c D^p y(s) \right) \right] \\ &= E_n + {}^{RL} I^q \left(x-s \right) {}^c D^q E_n - \\ & {}^{RL} I^q \left(x-s \right) [f \left(s, y_n(s), \,{}^c D^p y_n(s) \right) \\ & \left. - f \left(s, y(s), \,{}^c D^p y(s) \right) \right] \end{split}$$

$$= E_{n} - {}^{RL}I^{q} (s - x) {}^{c}D^{q} E_{n} - {}^{RL}I^{q} (x - s)[f(s, y_{n}(s), {}^{c}D^{p} y_{n}(s) - f(s, y(s), {}^{c}D^{p} y(s))]$$

we may suppose that the interval $x \in [a, b]$ may be scaled to $x \in [0,1]$ and hence $\sup|s - x| < 1$ therefore

$$\begin{split} E_{n+1}(x) &\leq E_n - E_n + E_n(0) - {}^{RL}I^q (x - s) \left(f(s, y_n(s), {}^cD^p y_n(s) - f(s, y(s), {}^cD^p y(s)) \right) \end{split}$$

with $E_n(0) = 0$. and hence using the definition of ^{RL} I^q, we have:

$$E_{n+1}(x) = \frac{\frac{-1}{\Gamma(q)} \int_0^x (x-s)^{q-1} [f(s, y_n(s), {}^c D^p y(s) - f(s, y_n(s), {}^c D^p y(s)] ds \dots (19)]}$$

Now, take the supremum norm to the both side of eq. (19), we get:

$$\begin{split} \|E_{n+1}(x)\| &\leq \frac{1}{\Gamma(q)} \int_{0}^{x} \|(x-s)^{q-1}\| \\ & \|f(s, y_{n}(s), {}^{c}D^{p} y_{n}(s) - \\ & f(s, y(s), {}^{c}D^{p} y(s)\| \, ds \\ &\leq \frac{1}{\Gamma(q)} \int_{0}^{x} (\|E_{n}\| + \|{}^{c}D^{q} E_{n}\|) ds \\ &\leq \frac{1}{\Gamma(q)} \int_{0}^{x} (\|E_{n}\| + c\|E_{n}\|) ds \\ &= \frac{L(1+c)}{\Gamma(q)} \int_{0}^{x} \|E_{n}(s)\| ds, n = 0, 1, ... \\ & \dots (20) \end{split}$$

If n = 0, then:

$$\begin{split} \|E_1\| &\leq \frac{L(1+c)}{\Gamma(q)} \int_0^x \|E_0\| ds = \frac{L(1+c)}{\Gamma(q)} \|E_0\| x\\ \text{If } n &= 1\\ \|E_2\| &\leq \frac{L(1+c)}{\Gamma(q)} \int_0^x \|E_1\| ds\\ &\leq \frac{L(1+c)}{\Gamma(q)} \int_0^x \frac{L(1+c)}{\Gamma(q)} \|E_0\| ds\\ &\leq \frac{L(1+c)}{\Gamma(q)} \int_0^x \frac{L(1+c)}{\Gamma(q)} \|E_0\| ds\\ &= \frac{L^2(1+c)^2}{\Gamma^2(q)} \|E_0\| \frac{x^2}{2} \end{split}$$

Hence, in general, using mathematical induction, we have:

$$\begin{split} \|E_n\| &\leq \left(\frac{L(1+c)}{\Gamma(q)}\right)^n \|E_0\| \frac{x^n}{n!} \\ \text{Since } L &< \frac{\Gamma(q)}{1+c} \text{ and therefore as } n \rightarrow \\ & \infty, \text{ we have } \left(\frac{L(1+c)}{\Gamma(q)}\right)^n \rightarrow 0 \quad \text{ and } \quad \frac{1}{n!} \rightarrow \\ & 0 \text{ and therefore } \|E_n(s)\|_{\infty} \rightarrow \\ & 0, \text{ i. e. }, y_n(x) \rightarrow y(x). \quad \blacksquare \end{split}$$

6. Numerical Simulation

In this section Numerical simulation for two illustrative examples, which are for linear and nonlinear fractional order BVPs:

Example 1:

Consider the linear fractional order BVP ^c D^{1.5}y + y = 4.513516 x^{0.5} $-\frac{0.282094}{..15}$ +

$$1 + 2x^2, x \in [0,1]$$
 ...(21)

With two-points boundary conditions y(0) = 1, y(1) = 3

For comparison purpose the exact solution is given by:

$$y(x) = 1 + 2x^2$$

According to the VIM, we derive a correction functional as follows:

$$y_{n+1}(x) = y_n(x) + {}^{RL}I^{1.5}(s-x) \left[{}^{c}D^{1.5}y_n + y_n - \left(4.513516 \ x^{0.5} - \frac{0.282094}{x^{1.5}} + 1 + 2x^2 \right) \right], x \in [0,1] \qquad \dots (30)$$

Now, we begin with an arbitrary initial approximation:

 $y_0(x) = A + Bx$

where A and B are constants to be determined. By VIM (30) we have:

$$y_{1}(x) = y_{0}(x) + {}^{\text{RL}} I^{1.5}(s-x) {}^{c} D^{1.5} y_{0}(s) +
\frac{1}{2} y_{0}(s) - (4.513516 x^{\frac{3}{2}} -
\frac{0.282094}{x^{1.5}} + 1 - 2x^{2}) \}
= A + Bx + {}^{\text{RL}} I^{1.5}(s-x) {}^{c} D^{1.5}(A + Bx) + \frac{1}{2}(A + Bx) -
(4.513516 x^{\frac{3}{2}} - \frac{0.282094}{x^{1.5}} + 1 -
2x^{2}) \}$$

By imposing the boundary conditions at x = 0 and x = 1 yields A = 1 and B = -0.4694032.

Now by using computer programs written in Mathcad 14the following results for $y_1(x)$ and $y_2(x)$ and $y_3(x)$ are obtained. In table (1) comparison between the exact and approximate solution of the BVP (21).

Exact and approximation solutions of example 1					
x	$y_e(x)$	$y_1(x)$	$y_2(x)$	$y_3(x)$	
0	1	1	1	1	
0.2	1.08	1.058	1.069	1.077	
0.4	1.32	1.299	1.285	1.315	
0.6	1.72	1.613	1.657	1.718	
0.8	2.28	2.246	2.279	2.281	
1	3	3	3	3	

Table (1)Exact and approximation solutions of example 1

Example 2:

Consider the nonlinear fractional order BVP:

^c D^{1.5}y = y² + ^c D^{1/4}y + (4.513516x^{0.5} -

$$\frac{0.2820947}{x^{1.5}} - 4x^{2} - 4x^{4} - \frac{1}{\frac{1}{x^{4}}\Gamma(\frac{3}{4})} - \frac{64x^{7}}{5\Gamma(\frac{3}{4})} - 1), x \in [0,1] \qquad \dots (31)$$

with two-points boundary condition y(0) = 1, y(1) = 3.

For comparison purpose, the exact solution is given by:

 $\mathbf{y}(\mathbf{x}) = 1 + 2\mathbf{x}^2$

According to the VIM we derive a correction functional as follows:

$$y_{n+1}(x) = y_n(x) + {}^{RL}I^{1.5}\lambda \{ {}^{c}D^{1.5}y_n - y_n^2 - {}^{c}D^{\frac{1}{4}}y - [4.513516x^{0.5} - \frac{0.2820947}{x^{1.5}} - 4x^2 - 4x^4 - \frac{1}{x^{\frac{1}{4}}\Gamma(\frac{3}{4})} - \frac{64x^{\frac{7}{4}}}{5\Gamma(\frac{3}{4})} - 1] \} \qquad \dots (32)$$

Now, we begin with an arbitrary initial approximation:

 $y_0(x) = A + Bx$

where A and B are constants to be determined. By the VIM (32), we have:

$$y_{1}(x) = y_{0}(x) + {}^{\text{RL}} I^{1.5} \lambda \begin{cases} {}^{c} D^{1.5} y_{0} - \\ & y_{0}^{2} - {}^{c} D^{\frac{1}{4}} y - \left[4.513516x^{0.5} - \right. \\ & \frac{0.2820947}{x^{1.5}} - 4x^{2} - 4x^{4} - \frac{1}{x^{\frac{1}{4}} \Gamma(\frac{3}{4})} - \\ & \frac{64x^{\frac{7}{4}}}{5\Gamma(\frac{3}{4})} - 1 \end{bmatrix} \\ = A + Bx + {}^{\text{RL}} I^{1.5} \lambda \{ {}^{c} D^{1.5} (A + Bx) - (A + Bx)^{2} - {}^{c} D^{\frac{1}{4}} (A + Bx) - [4.513516x^{0.5} - \\ & \frac{0.2820947}{x^{1.5}} - 4x^{2} - 4x^{4} - \frac{1}{x^{\frac{1}{4}} \Gamma(\frac{3}{4})} - \\ & \frac{64x^{\frac{7}{4}}}{5\Gamma(\frac{3}{4})} - 1] \} \end{cases}$$

By imposing the boundary conditions at x = 0 and x = 1 yields A = 1 and B = -0.058927.

Now by using computer programs written in Mathcad 14, the following results for $y_1(x)$ and $y_2(x)$ and $y_3(x)$ are obtained. In table (2) comparison between the exact and approximate solution of the BVP (31).

Exact and approximation solutions of example 2					
x	$y_e(x)$	$y_1(x)$	$y_2(x)$	$y_3(x)$	
0	1	1	1	1	
0.2	1.08	1.044	1.045	1.074	
0.4	1.32	1.225	1.257	1.291	
0.6	1.72	1.597	1.681	1.718	
0.8	2.28	2.236	2.253	2.282	
1	3	3	3	3	

Table (2)Exact and approximation solutions of example 2

Remark 1:

It is clear that as $n \longrightarrow \infty$, the sequence of iterated solutions will converge to the exact solution $y(x) = 1 + 2x^2$.

7. Conclusions

The VIM, as it is known, is a very accurate method, which may give the exact solution in a few steps, but in some cases it requires more calculations that will add some difficulties to the problem under consideration.

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