

# A Walsh Series Method For Solving Integro-Differential Equation

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## Abstract

In this paper, we use the orthonormality properties of the Walsh functions to give a new method for solving the initial value problem associated with the ordinary differential equation (with constant coefficients or with non-constant coefficients). This approach is named a Walsh series method and it is illustrated with some examples.

## Introduction

The Walsh functions are initiated by Rademacher [1] and independently developed by Walsh [2] in the early nineteen twenties. In recent years, the Walsh theory has been innovated and applied to various fields in engineering and science[3].

### Rademacher and Walsh Functions, [4]:

Rademacher's function  $r_i(t)$  is a set of square waves of unit height with period equal to  $\frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \dots, 2^{-n}$  respectively. Alternatively, we state that the number of cycles of the square waves of  $r_i(t)$  is  $2^{n-i}$ . It is noted that the set is not complete since, except for  $r_0(t)$ , the set involves only functions which are odd about  $t = \frac{1}{2}$ .

In 1923, Walsh independently developed a complete set known as Walsh functions. The set of Walsh functions  $\phi_i(t)$  and the set of Rademacher functions have the following relation:

$$\begin{aligned}\phi_i(t) &= r_i(t) \\ \phi_i(t) &= r_i(t)[r_i(t)] \\ \phi_i(t) &= [r_i(t)]^i[r_i(t)] \\ \phi_i(t) &= [r_i(t)]^i[r_i(t)]^i[r_i(t)]^i \\ &\vdots \\ \phi_n(t) &= [r_n(t)]^i[r_{n-1}(t)]^i[r_{n-2}(t)]^i\end{aligned}$$

where  $i = [\log_2 n] + 1$  in which  $[.]$  means taking the greatest integer of  $[.]$ . Therefore

$$n = b_{n-1}2^{n-1} + b_{n-2}2^{n-2} + \dots + b_12^1$$

where  $b_{n-1}b_{n-2}\dots b_1$  is the binary expression of  $n$ .

## The Approach

Consider the first order ordinary integro-differential equation:

$$f'(x) = g(x) + \int_a^x k(x,y)f(y)dy \quad (1)$$

with  $f(0) = \alpha$ .

where  $g(x), k(x,y)$  are known functions of  $x$  and  $x,y$  respectively. The problem here is to determine the function  $f(x)$ .

The approach is based on approximating the first derivative of the unknown solution  $f'(x)$  into a Walsh series:

$$f'(x) = c_0 \phi_0(x) + c_1 \phi_1(x) + \dots + c_n \phi_n(x)$$

where  $c_i$  are the unknown coefficients of the Walsh series of  $f'(x)$  that must be determined. Then  $f(x)$  is obtained by:

$$f(x) = \int f'(x) - f(0)$$

$$f(x) = c_0 \int \phi_0(x)dx + c_1 \int \phi_1(x)dx + \dots + c_n \int \phi_n(x)dx - f(0)$$

And by using the same approach described above, one can obtain:

$$f(x) = \sum_{i=0}^n c_i \sum_{j=0}^i b_j \phi_j(x) + f(0)$$

where  $\int \phi_i(x)dx = \sum_{j=0}^i b_j \phi_j(x)$  and  $\{b_j\}_{j=0}^i$  are known parameters that can be found similar to the above.

Also, express  $g(x), x$  &  $y$  appeared in the function  $k(x,y)$  as a linear combinations of the Walsh functions with known coefficients. Then by substituting the above functions  $f'(x), f(x)$ ,  $x, y$  appeared in the known function  $k(x,y)$  and  $g(x)$  into eq (4) and taking the scalar product with  $\phi_i(x)$ , for all  $i=0,1,\dots,n$ , we obtained a linear system of  $n$  equations with  $n$  variables  $\vec{c} = (c_0, c_1, \dots, c_n)$ . Hence by solving this system by any suitable method, the values of  $\vec{c} = (c_0, c_1, \dots, c_n)$  are computed.

To illustrate this approach, we give the following example:

### Example

Consider the first order ordinary integro-differential equation

$$f'(x) = x + \int_0^x (2-x)f(y)dy \quad (2)$$

with  $f(0)=0$ .

Approximate  $f'(x)$  as:  $f'(x) = c_0\phi_0(x) + c_1\phi_1(x)$

$$\text{Therefore, } f(x) = \int_0^x [f'(x) + f(0)] dx$$

Thus

$$\begin{aligned} f(x) &= \int_0^x [c_0\phi_0(x) + c_1\phi_1(x)] dx = c_0 \int_0^x \phi_0(x) dx + c_1 \int_0^x \phi_1(x) dx \\ &= c_0 \left( \frac{1}{2}\phi_0(x) - \frac{1}{4}\phi_0(x) \right) + c_1 \left( \frac{1}{4}\phi_1(x) \right) \\ &= \left( \frac{1}{2}c_0 + \frac{1}{4}c_1 \right) \phi_0(x) + \left( -\frac{1}{4}c_0 \right) \phi_1(x) \end{aligned}$$

Also, write the variable  $x$  as  $x = \frac{1}{2}\phi_0(x) - \frac{1}{4}\phi_1(x)$

Next, substitute the function  $f(x), f'(x)$  &  $x$  into eq.(2) to obtain:

$$\begin{aligned} c_0\phi_0(x) + c_1\phi_1(x) - \frac{1}{2}c_0\phi_0(x) + \frac{1}{4}c_1\phi_1(x) &= \\ 2 \left( 1 - \frac{1}{2}\phi_0(x) + \frac{1}{4}\phi_1(x) \right) \left( \frac{1}{2}c_0 - \frac{1}{4}c_1 \right) &= 0 \quad (3) \end{aligned}$$

and by integrating both sides of eq.(3) from 0 to 1 and use the following facts:-

$$\int_0^1 \phi_i(x) dx = 1 \text{ and } \int_0^1 \phi_i^2(x) dx = 0, i = 0, 1, 2, \dots$$

we obtain:

$$c_0 - \frac{1}{2} + 2 \left( 1 - \frac{1}{2} \right) \left( \frac{1}{2}c_0 - \frac{1}{4}c_1 \right) = 0$$

Hence

$$2c_0 - c_1 = 2$$

and by multiplying eq.(3) by  $\phi_1(x)$  and then integrating from 0 to 1 to give

$$-2c_0 + 7c_1 = -2$$

and by solving the above equations to give  $c_0 = 0$ , and then  $c_1 = 1$  and hence the solution  $y(x) = x$  is the approximate solution of the above example which is agree with the exact solution  $y'(x) = x$ .

## References

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