# EXISTENCE AND UNIQUENESS FOR A CLASS OF SEMILINEAR INITIAL VALUE CONTROL PROBLEMS IN SUITABLE BANACH SPACES 

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#### Abstract

The local existence and uniqueness of S-classical solution (semi-classical solution) for a class of semilinear initial value control problems in suitable Banach spaces have been discussed and proved. The theoretical results are depending on the theory of analytic semigroup and Banach contraction principle.


Keywords: S-classical solution (semi-classical solution), control problem in infinite dimensional spaces, fixed point theorem and analytic semigroup theory.

## Introduction

Byszewski in 1991 [1], has study the local existence and uniqueness of the mild solution to the semilinear initial value problem:

$$
\begin{align*}
& \frac{\mathrm{dv}}{\mathrm{dt}}+\operatorname{Av}(\mathrm{t})=\mathrm{f}(\mathrm{t}, \mathrm{v}(\mathrm{t}))  \tag{1}\\
& \mathrm{v}(0)=\mathrm{v}_{0}
\end{align*}
$$

Where A is the infinitesimal generator of a $\mathrm{C}_{0}$ semigroup (strongly continuous semigroup) defined from $D(A) \subset X$ into $X(X$ is suitable Banach space) and f is a nonlinear continuous map define from [0,r) $\times \mathrm{X}$ into X. Eduardo [2] in 2001, has study the local existence and uniqueness of the of S-classical solution (Semi-classical Solution) to the problem defined in (1).

## Definition :

A function $x \in \mathrm{C}([0, \mathrm{r}): \mathrm{X})$ is said to be an S classical solution (semi-classical solution) to the semilinear initial value problem defined in (1), if $x(t)$ has the following form:

$$
\begin{equation*}
x(t)=T(t) x_{0}+\int_{0}^{t} T(t-s) f(s, x(s)) d s \tag{2}
\end{equation*}
$$

Satisfies the following conditions: $\mathrm{x}(0)=\mathrm{x}_{0}$, $\frac{d}{d t} x(t)$ is continuous on $(0, r), x(t) \in D(A)$ for all $t \in(0, r)$ and $x($.$) satisfies equation (1) on$ ( $0, ~ r$ ).

Manaf [3] in 2005, has study the local existence and uniqueness of the mild solution to the semilinear initial value control problem:

$$
\left.\begin{array}{l}
\frac{\mathrm{dx}}{\mathrm{dt}}+\mathrm{Ax}(\mathrm{t})=\mathrm{f}(\mathrm{t}, \mathrm{x}(\mathrm{t}))+ \\
\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{~h}(\mathrm{t}-\mathrm{s}) \mathrm{g}(\mathrm{~s}, \mathrm{x}(\mathrm{~s})) \mathrm{ds}+(\mathrm{B} w)(\mathrm{t}), \mathrm{t}>0 \\
\mathrm{x}(0)=\mathrm{x}_{0}
\end{array}\right\}
$$

where $A$ is the infinitesimal generator of a $C_{0}$ semigroup defined from $D(A) \subset X$ into $X$ and $f$ and $g$ are a nonlinear continuous maps defined from $[0, \mathrm{r}) \times \mathrm{X}$ into $\mathrm{X}, \mathrm{h}$ is the real valued continuous function defined from [0,r) into $R$ where $R$ is the real number and $B$ is a bounded linear operator define from O into X . Where O is a Banach space and $w($.$) be the$ arbitrary control function is given in $\mathrm{L}^{\mathrm{p}}([0$, $\mathrm{r}): \mathrm{O}$ ), a Banach space of control functions with $\|w(\mathrm{t})\|_{\mathrm{o}} \leq \mathrm{k}_{1}$, for $0 \leq \mathrm{t}<\mathrm{r}$.

## Definition :

A continuous function $\mathrm{X}_{w}$ is said to be a mild solution to the semilinear initial value problem defined in (3) given by:

$$
\begin{aligned}
& x_{w}(t)=T(t) u_{0}+ \\
& \int_{s=0}^{t} T(t-s)\left[(B w)(s)+f\left(s, x_{w}(s)\right)+\int_{s=0}^{t} h(s-\tau) g\left(s, x_{w}(\tau)\right) d \tau\right] d s \\
& \forall w \in L^{p}([0, r): O)
\end{aligned}
$$

In the present paper, the S -classical solution (semi-classical solution) of the semilinear initial value control problem defined in (3) will be developed by the following definition:

## Definition :

A function $v \in C([0, r): X)$ is said to be an S-classical solution (semi-classical solution) to the semilinear initial value problem defined in (3), if $\mathrm{v}(\mathrm{t})$ has the following form:
$\mathrm{v}_{\mathrm{w}}(\mathrm{t})=\mathrm{T}(\mathrm{t}) \mathrm{u}_{0}+$
$\int_{s=0}^{t} T(t-s)\left[(B w)(s)+f\left(s, v_{w}(s)\right)+\int_{s=0}^{t} h(s-\tau) g\left(s, v_{w}(\tau)\right) d \tau\right] d s$
$\forall \mathrm{wL}$ ( $(0, \mathrm{r}): \mathrm{O})$
Satisfies the following conditions: $\mathrm{v}_{w}(0)=\mathrm{x}_{\mathrm{o}}$, $\frac{d}{d t} v_{w}(t)$ is continuous on $(0, r), \quad v_{w}(t) \in D(A)$
for all $t \in(0, r)$ and $\mathrm{v}_{w}($.$) satisfies equation (3)$ on ( $0, \mathrm{r}$ ).

Throughout this paper X will be a Banach space equipped with the norm $\|$.$\| and the$ operator $\mathrm{A}: \mathrm{D}(\mathrm{A}) \subset \mathrm{X} \rightarrow \mathrm{X}$ will be the infinitesimal generator of an analytic semigroup of bounded linear operators $\{T(t)\}_{t \geq 0}$ on $X$. For the theory of analytic semigroup, refer to Pazy [4], Jerome [5] and Balachandran [6]. The books of Pazy [4], Krien [7] and Fitzgibbon [8] contained therein, give a good account of important results. We mention here only some notation and properties essential to our purpose, In particular, we assume that $\{\mathrm{T}(\mathrm{t})\}_{\mathrm{t} 20}$ is an analytic semigroup generated by infinitesimal generator $A$ and $0 \in \rho(A)$, ( $\rho(A)$ stands for resolvent set).In this case it is possible to define the fractional power $(-\mathrm{A})^{\alpha}$, for $0<\alpha<1$, as a closed linear operator with domain $\mathrm{D}\left((-\mathrm{A})^{a}\right)$ is dense in X and the expression $\|x\|_{\alpha}=\left\|(-\mathrm{A})^{\alpha} \mathrm{x}\right\|_{\mathrm{x}}$,
Defines a norm on $\mathrm{D}\left((-\mathrm{A})^{\alpha}\right)$.Hereafter we represent by $X_{\alpha}$ the space $\mathrm{D}\left((-\mathrm{A})^{\alpha}\right)$ endowed with the norm $\left\|\left\|\|_{\alpha}\right.\right.$.

## Preliminaries

## Definition :

A family $\{\mathrm{T}(\mathrm{t})\}_{\mathrm{t} \geq 0}$ of bounded linear operators on a Banach space X is called a semigroup on X if it satisfies the following conditions:
$\mathrm{T}(\mathrm{t}+\mathrm{s})=\mathrm{T}(\mathrm{t}) \mathrm{T}(\mathrm{s}), \forall \mathrm{t}, \mathrm{s} \geq 0 \mathrm{~T}(0)=\mathrm{I},(\mathrm{T}(0)$ is the identity operator on X ).

## Definition :

A family $\{\mathrm{T}(\mathrm{t})\}_{\geq 20}$ is said to be an analytic semigroup if the following conditions are satisfy:
(i) $\mathrm{t} \rightarrow \mathrm{T}(\mathrm{t})$ is analytic in some sector $\Delta$, where $\Delta$ is a sector containing the nonnegative real axis.
(ii) $\mathrm{T}(0)=\mathrm{I}$ and

$$
\lim _{t t_{0}}\|T(t) x-x\|_{x}=0, \forall x \in X
$$

(iii) $\mathrm{T}(\mathrm{t}+\mathrm{s})=\mathrm{T}(\mathrm{t}) \mathrm{T}(\mathrm{s}), \forall \mathrm{t}, \mathrm{s} \geq 0$.

## Definition :

A semigroup $\{\mathrm{T}(\mathrm{t})\}_{\mid \geq 0}$ on a Banach space X is called strongly continuous semigroup of bounded linear operators or ( $\mathrm{C}_{0}$ semigroup) if

The map $R^{+}$э $t \longrightarrow T(t) \in L(X)$, satisfies the following conditions:
(i) $\mathrm{T}(\mathrm{t}+\mathrm{s})=\mathrm{T}(\mathrm{t}) \mathrm{T}(\mathrm{s}), \forall \mathrm{t}, \mathrm{s} \geq 0$.
(ii) $\mathrm{T}(0)=\mathrm{I}$.
(iii) $\lim _{t, 0}\|T(t) x-x\|=0$, for every $x \in X$.

## Definition :

If -A is the infinitesimal generator of bounded analytic semigroup then the fractional power $\mathrm{A}^{-\alpha}$ exist for $\alpha>0$.

## Definition :

Let -A be the infinitesimal generator of an analytic semigroup $T(t)$ if $0 \in \rho(A)$, then:
(a) $\mathrm{T}(\mathrm{x}): \mathrm{X} \longrightarrow \mathrm{D}\left(\mathrm{A}^{\alpha}\right)$, for every $\mathrm{t}>0$ and $\alpha \geq 0$.
(b) For every $\mathrm{x} \in \mathrm{D}\left(\mathrm{A}^{\alpha}\right)$, we have $\mathrm{T}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{x}=$ $\mathrm{A}^{\alpha} \mathrm{T}(\mathrm{t}) \mathrm{x}$.
(c) For every $t \geq 0$, the operator $\mathrm{A}^{\alpha} \mathrm{T}(\mathrm{t})$ is bounded and $\left\|\mathrm{A}^{\alpha} \mathrm{T}(\mathrm{t})\right\| \leq \mathrm{M}_{\mathrm{L}} \mathrm{t}^{-\alpha}$.
(e) Let $0<\alpha \leq 1$ and $x \in D\left(A^{\alpha}\right)$ then $\|T(t) x-x\| \leq C_{\alpha} t^{\alpha}\left\|^{\alpha}{ }^{\alpha}\right\|_{x}$, where $C_{\alpha}$ is the positive constant depend on $\alpha$.

## Definition :

Suppose X is a Banach space. A mapping $\mathrm{T}: \mathrm{X} \longrightarrow \mathrm{X}$ is said to be strict contraction, with strict contraction constant L, if $\|\mathrm{Tx}-\mathrm{Ty}\|_{\mathrm{X}} \leq \mathrm{L}\|\mathrm{x}-\mathrm{y}\|_{\mathrm{X}}, \quad \forall \mathrm{x}, \mathrm{y} \in \mathrm{X}$, where $0<$ $\mathrm{L}<1$.

## Definition Banach contraction principle:

Let M is a closed nonempty set in the Banach space X over k , where k are a scalar field and the operator $\mathrm{T}: \mathrm{M} \longrightarrow \mathrm{M}$ is strict contraction operator then T has a unique fixed point.

## Definition :

Let I be an interval, A function $\mathrm{f}: \mathrm{I} \longrightarrow \mathrm{X}$, where X is a Banach space is said to be Hölder continuous with exponent $\vartheta, 0<\vartheta<$ lon I , if there is a constant L such that $\|f(t)-f(s)\|_{X} \leq L|t-s|^{9}$, for $s, t \in I$.

## Main Result

It should be notice that the local existence and uniqueness of S-classical solution (Semiclassical Solution) of the semilinear initial value control problem defined in (3) developed, by assuming the following assumptions:
A. -A be the infinitesimal generator of bounded analytic semigroup $\{S(t)\}_{\llcorner\geq 0}$ and 0 $\in \rho(-\mathrm{A})$.where the operator -A define from $D(-A) \subset X$ into $X,(X$ is a Banach space).
B. Let $U$ be an open subset of $[0, r) \times X_{\alpha}$, for $0<r \leq \infty$. Where $\mathrm{X}_{\alpha}$ is a Banach space being dense in X .
C. For every $(t, x) \in U$, there exists $a$ neighborhood $\mathrm{G} \subset \mathrm{U}$ of $(\mathrm{t}, \mathrm{x})$, the nonlinear maps $\quad \mathrm{f}, \quad \mathrm{g}:[0, \mathrm{r}) \times \mathrm{X}_{\alpha} \longrightarrow \mathrm{X}$ satisfy the locally Lipchitize condition with respect to second argument,
$\|f(t, u)-f(s, v)\|_{x} \leq L_{0}\|v-u\|_{\alpha}$
$\|\mathrm{g}(\mathrm{t}, \mathrm{u})-\mathrm{g}(\mathrm{s}, \mathrm{v})\|_{\mathrm{x}} \leq \mathrm{L}_{1}\|\mathrm{v}-\mathrm{u}\|_{\alpha}$,
for all $(\mathrm{t}, \mathrm{u})$ and $(\mathrm{s}, \mathrm{v}) \in \mathrm{G}$.
D. For $\mathrm{t}^{\prime \prime}>0,\|f(\mathrm{t}, \mathrm{v})\|_{\mathrm{x}} \leq \mathrm{B}_{1},\|\mathrm{~g}(\mathrm{t}, \mathrm{v})\|_{\mathrm{x}} \leq \mathrm{B}_{2}$, for $0 \leq t \leq t^{\prime \prime}$ and for every $v \in X_{\alpha}$.
E. For $t^{\prime \prime \prime}>0,\|S(t)-I\|\left\|A^{\alpha} u_{0}\right\| \leq \delta^{\prime}$, Where $\delta^{\prime}<\delta, 0 \leq t \leq \mathrm{t}^{\prime \prime \prime}$.
F . h is continuous function which at least $h \in L^{1}([0, r): R)$, Where $R$ is the real number.
G. $w($.$) be the arbitrary control function is$ given in $L^{\mathrm{P}}([0, \mathrm{r}): \mathrm{O})$, a Banach space of control functions with O as a Banach space and here B is a bounded linear operator from O into X and $\|w(\mathrm{t})\|_{\mathrm{o}} \leq \mathrm{k}_{1}$, for $0 \leq \mathrm{t}<\mathrm{r}$.
H. Let $t_{1}>0$ such that $t_{1}=\mathrm{min}$ $\left\{\mathrm{t}^{\prime}, \mathrm{t}^{\prime \prime}, \mathrm{t}^{\prime \prime \prime}, \mathrm{r}\right\}$, satisfy the condition $\mathrm{t}_{1} \leq\left\{\left[\mathrm{K}_{0} \mathrm{~K}_{1}+\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)+\right.\right.$
(H.i)

$$
\begin{aligned}
& \text { (H.i) } \left.\left.\quad \mathrm{h}_{\mathrm{t}_{1}}\left(\delta \mathrm{~L}_{1}+\mathrm{B}_{2}\right)\right]^{-1} \mathrm{C}_{\alpha}^{-1}(1-\alpha)\left(\delta-\delta^{\prime}\right)\right\}^{\frac{1}{1-\alpha}} \\
& \Rightarrow \Rightarrow^{\mathrm{t}_{1}^{1-\alpha} \leq\left[\mathrm{K}_{0} \mathrm{~K}_{1}+\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)+\right.} \begin{array}{l}
\left.\mathrm{h}_{\mathrm{t}_{1}}\left(\delta \mathrm{~L}_{1}+\mathrm{B}_{2}\right)\right]^{-1} \mathrm{C}_{\alpha}^{-1}(1-\alpha)\left(\delta-\delta^{\prime}\right)
\end{array} .
\end{aligned}
$$

I. There exist $\mathrm{C}_{2} \geq 0$ and $0<\vartheta \leq 1$ such that: $|\mathrm{h}(\mathrm{t})-\mathrm{h}(\mathrm{s})| \leq \mathrm{C}_{3}|\mathrm{t}-\mathrm{s}|^{\mu}$, for all $\mathrm{t}, \mathrm{s} \in\left[0, \mathrm{t}_{1}\right]$.
J. There exist $\mathrm{R}_{0} \geq 0$ and $0<\xi \leq 1$ such that: $\|w(\mathrm{t})-w(\mathrm{~s})\|_{0} \leq \mathrm{R}_{0}|\mathrm{t}-\mathrm{s}|^{\xi^{\xi}}$, for all $\mathrm{t}, \mathrm{s} \in\left[0, \mathrm{t}_{1}\right]$.

## Main Theorem:

Assume that hypotheses (A)-(J) are hold, then for every $\mathrm{v}_{0} \in \mathrm{X}_{\alpha}$, there exists a fixed number $t_{1}, 0<t_{1}<r$, such that the initial value control problem defined in (3) has a unique $S$ classical solution $\mathrm{v}_{w} \in \mathrm{C}\left(\left[0, \mathrm{t}_{1}\right]: \mathrm{X}\right)$, for every control function $w(.) \in \mathrm{L}^{\mathrm{p}}\left(\left[0, \mathrm{t}_{1}\right]: \mathrm{O}\right)$.

## Proof:

Without loss of generality, we may suppose $\mathrm{r}<\infty$, because we are concerned here with the local existence only.

For a fixed point $\left(0, \mathrm{v}_{0}\right)$ in the open subset U of $[0, \mathrm{r}) \times \mathrm{X}_{\alpha}$, we choose $\delta>0$ such that the neighborhood $G$ of the point $\left(0, \mathrm{v}_{0}\right)$ define as follow:
$\mathrm{G}=\left\{(\mathrm{t}, \mathrm{x}) \in \mathrm{U}: 0 \leq \mathrm{t} \leq \mathrm{t}^{\prime},\left\|\mathrm{v}-\mathrm{v}_{0}\right\|_{\alpha} \leq \delta\right\} \subset \mathrm{U}\{$ since U is an open subset of $\left.[0, \mathrm{r}) \times \mathrm{X}_{\alpha}\right\}$.

It is clear that $\left\|A^{\alpha} S(t)\right\| \leq C_{\alpha} t^{-\alpha}$, for $t>0$, see \{theorem (1.8.7) in [4]\}.

Where $\mathrm{C}_{\alpha}$ is a positive constant depending on $\alpha$ and assume
$\mathrm{h}_{\mathrm{r}}=\int_{0}^{\mathrm{r}}|\mathrm{h}(\mathrm{s})| \mathrm{ds}$.
Set $Y=C\left(\left[0, t_{1}\right]: X\right)$, then $Y$ is a Banach space with the supremum norm: $\|y\|_{Y}$ $=\sup _{0 \leq t \leq t_{1}}\|y(t)\|_{x}$.

Let $S_{w}$ be the nonempty subset of $Y$, define as follow:

$$
\begin{align*}
\mathrm{S}_{w}= & \left\{\mathrm{x}_{w} \in \mathrm{Y}: \mathrm{x}_{w}(0)=\mathrm{A}^{\alpha} \mathrm{x}_{0},\right. \\
& \left.\left\|\mathrm{x}_{w}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \delta, 0 \leq \mathrm{t} \leq \mathrm{t}_{1}\right\} \tag{4}
\end{align*}
$$

To prove the closedness of $S_{w}$ as a subset of Y. Let $X_{w}^{n} \in S_{w}$, such that
$\mathrm{X}_{w}^{\mathrm{n}} \xrightarrow{\text { P.C. }} \mathrm{X}_{w}$ as $\mathrm{n} \longrightarrow \infty$, we must prove that $\mathrm{x}_{w} \in \mathrm{~S}_{w}$, where (P.C) stands for point wise convergence.

Since $\mathrm{X}_{w}^{\mathrm{n}} \in \mathrm{S}_{w} \Rightarrow \mathrm{X}_{w}^{\mathrm{n}} \in \mathrm{Y}, \mathrm{X}_{w}^{\mathrm{n}}(0)=\mathrm{A}^{\alpha} \mathrm{x}_{0} \quad$ and $\left\|\mathrm{X}_{w}^{\mathrm{n}}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \delta, 0 \leq \mathrm{t} \leq \mathrm{t}_{1}$.

Since $\quad \mathrm{X}_{w}^{\mathrm{n}} \xrightarrow{\text { U.C. }} \mathrm{X}_{w}$, hence $\mathrm{X}_{w} \in \mathrm{Y}$. where (U.C) stands for the uniform convergence, and also since $\mathrm{X}_{w}^{\mathrm{n}} \xrightarrow{\text { U.C. }} \mathrm{X}_{w}$ $\Rightarrow\left\|\mathrm{X}_{w}^{\mathrm{n}}-\mathrm{x}_{w}\right\|_{\mathrm{Y}} \longrightarrow 0$, as $\mathrm{n} \longrightarrow \infty$
$\left\|\mathrm{X}_{w}^{\mathrm{n}}-\mathrm{X}_{w}\right\| \mathrm{Y}=\sup _{0 \leq \mathrm{t} \leq \mathrm{t}_{1}}\left\|\mathrm{x}_{\mathrm{w}}^{\mathrm{n}}(\mathrm{t})-\mathrm{x}_{\mathrm{w}}(\mathrm{t})\right\|_{\mathrm{x}} \longrightarrow 0$, as
$\mathrm{n} \longrightarrow \infty,\left\{B y\|y\|_{\mathrm{Y}}=\sup _{0 \leq \mathrm{t} \mathrm{t}_{1}}\|\mathrm{y}(\mathrm{t})\|_{\mathrm{x}}\right\}$.
Implies that $\left\|\mathrm{X}_{w}^{\mathrm{n}}(\mathrm{t})-\mathrm{X}_{w}(\mathrm{t})\right\|_{\mathrm{x}} \longrightarrow 0$, as $\mathrm{n} \longrightarrow \infty$, for every $0 \leq t \leq t_{1}$,
i.e., $\lim _{\mathrm{n} \rightarrow \infty} \mathrm{X}_{w}^{\mathrm{n}}(\mathrm{t})=\mathrm{x}_{w}(\mathrm{t}), \forall 0 \leq \mathrm{t} \leq \mathrm{t}_{1}$
$\Rightarrow \lim _{\mathrm{n} \rightarrow \infty} \mathrm{x}_{w}^{\mathrm{n}}(0)=\mathrm{x}_{w}(0)\{\operatorname{by}(5)\}$
$\Rightarrow \lim _{\mathrm{n} \rightarrow \infty} \mathrm{A}^{\alpha} \mathrm{X}_{0}=\mathrm{X}_{w}(0)\left\{\right.$ since $\left.\mathrm{X}_{w}^{\mathrm{n}} \in \mathrm{S}\right\}$
$\Rightarrow \mathrm{A}^{\alpha} \mathrm{x}_{0}=\mathrm{X}_{w}(0)$
Notice that:
$\left\|\mathrm{x}_{w}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}}=\left\|\lim _{\mathrm{n} \rightarrow \infty} \mathrm{x}_{w}^{\mathrm{n}}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}},\{b \mathrm{by}$ (5) \}
$=\left\|\lim _{\mathrm{n} \rightarrow \infty} \mathrm{X}_{w}^{\mathrm{n}}(\mathrm{t})-\lim _{\mathrm{n} \rightarrow \infty} \mathrm{A}^{\alpha} \mathrm{X}_{0}\right\|_{\mathrm{x}}=\| \lim _{\mathrm{n} \rightarrow \infty}$
$\left(\mathrm{X}_{w}^{\mathrm{n}}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right)\left\|_{\mathrm{x}}=\lim _{\mathrm{n} \rightarrow \infty}\right\| \mathrm{X}_{w}^{\mathrm{n}}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0} \|_{\mathrm{x}}$
$\Rightarrow\left\|\mathrm{x}_{w}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \lim _{\mathrm{n} \rightarrow \infty} \delta$
$\left\{\right.$ since $\mathrm{X}_{w}^{\mathrm{n}} \in \mathrm{S}_{w}$ \}
$\Rightarrow\left\|\mathrm{x}_{w}(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \delta$, for $0 \leq \mathrm{t} \leq \mathrm{t}_{1}$.
We have got $S_{w}$ is closed subset of Y.
Now, define a map $\mathrm{F}_{w}: \mathrm{S}_{w} \longrightarrow \mathrm{Y}$, given by:

$$
\begin{aligned}
& \left(F_{w} x_{w}\right)(t)=S(t) A^{\alpha} u_{0}+ \\
& \int_{s=0}^{\mathrm{t}} \mathrm{~A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\left[\mathrm{f}\left(\mathrm{~s}, \mathrm{~A}^{-\alpha} \mathrm{x}_{w}(\mathrm{~s})\right)+\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{~h}(\mathrm{~s}-\tau) \mathrm{g}\left(\tau, \mathrm{~A}^{-\alpha} \mathrm{x}_{w}(\tau)\right) \mathrm{d} \tau\right] \mathrm{ds}+ \\
& \int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{~A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})(\mathrm{B} w)(\mathrm{s}) \mathrm{ds}
\end{aligned}
$$

To show that $\mathrm{F}_{w}\left(\mathrm{~S}_{w}\right) \subseteq \mathrm{S}_{w}$, let $\mathrm{X}_{w}$ be arbitrary element in $\mathrm{S}_{w}$ and let $\quad \mathrm{F}_{w} \mathrm{X}_{w} \in$ $\mathrm{F}_{w}\left(\mathrm{~S}_{w}\right)$.

To prove $\mathrm{F}_{w} \mathrm{X}_{w} \in \mathrm{~S}_{w}$ for arbitrary element $\mathrm{X}_{w}$ in $S_{w}$. From (4), notice that $\mathrm{F}_{w} \mathrm{x}_{w} \in \mathrm{Y}$ \{by the definition of the map $\left.\mathrm{F}_{w}\right\}$ And $\left(\mathrm{F}_{w} \mathrm{x}_{w}\right)(0)=\mathrm{A}^{\alpha} \mathrm{x}_{0}$ $\{$ by (6) $\}$.
Now we have got
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})=\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{X}}=$
$\| S(t) A^{\alpha} x_{0}-A^{\alpha} u_{0}+\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})(\mathrm{B} w)(\mathrm{s}) \mathrm{ds}$
$+\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\left[\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{~s})\right)+\right.$
$\left.\int_{s=0}^{t} h(s-\tau) g\left(\tau, \mathrm{~A}^{-\alpha} x_{w}(\tau)\right) d \tau\right] d s \|_{x}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}}=$
$\| S(t) A^{\alpha} \mathrm{X}_{0}-\mathrm{A}^{\alpha} \mathrm{X}_{0}+\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})(\mathrm{B} w)(\mathrm{s}) \mathrm{ds}$
$+\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\left[\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{x}_{w}(\mathrm{~s})\right)+\right.$
$\left.\int_{s=0}^{t} h(s-\tau) g\left(\tau, A^{-\alpha} x_{w}(\tau)\right) d \tau\right] d s+$
$\int_{s=0}^{t} A^{\alpha} S(t-s) f\left(s, x_{0}\right) d s-\int_{s=0}^{t} A^{\alpha} S(t-s) f\left(s, x_{0}\right) d s+$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left(\int_{s=0}^{t} h(s-\tau) g\left(\tau, x_{0}\right) d \tau\right) d s-$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left(\int_{s=0}^{t} h(s-\tau) g\left(\tau, x_{0}\right) d \tau\right) d s \|_{x}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|=\| \mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{x}_{0}-\mathrm{A}^{\alpha} \mathrm{x}_{0}+$ $\int_{s=0}^{t} A^{\alpha} S(t-s)(B w)(s) d s$
$\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\left[\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{x}_{w}(\mathrm{~s})\right)-\mathrm{f}\left(\mathrm{s}, \mathrm{x}_{0}\right)\right] \mathrm{ds} \quad+$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left(\int_{s=0}^{t} h(s-\tau)\left[g\left(\tau, A^{-\alpha} x_{w}(\tau)\right)-\right.\right.$ $\left.\left.\mathrm{g}\left(\tau, \mathrm{x}_{0}\right)\right] \mathrm{d} \tau\right) \mathrm{ds}+$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left(f\left(s, x_{0}\right)+\int_{\tau=0}^{s} h(s-\tau) g\left(\tau, x_{0}\right) d \tau\right) d s \|_{x}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq\left\|\mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{x}_{0}-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}}+$ $\int_{\mathrm{s}=0}^{\mathrm{t}}\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\right\|\|(\mathrm{B} w)(\mathrm{s})\| \mathrm{ds} \quad+$ $\int_{\mathrm{s}=0}^{\mathrm{t}}\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\right\|\left\|\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{x}_{w}(\mathrm{~s})\right)-\mathrm{f}\left(\mathrm{s}, \mathrm{x}_{0}\right)\right\| \mathrm{ds}+$ $\int_{s=0}^{t}\left\|A^{\alpha} S(t-s)\right\|\left(\int_{s=0}^{t}|h(s-\tau)| \| g\left(\tau, A^{-\alpha} x_{w}(\tau)\right)\right.$ $\left.-\mathrm{g}\left(\tau, \mathrm{x}_{0}\right) \| \mathrm{d} \tau\right) \mathrm{ds}+$
$\int_{s=0}^{t}\left\|A^{\alpha} S(t-s)\right\|$.
$\cdot\left(\left\|f\left(\mathrm{~s}, \mathrm{x}_{0}\right)\right\|+\int_{\tau=0}^{\mathrm{s}}|\mathrm{h}(\mathrm{s}-\tau)|\left\|\mathrm{g}\left(\tau, \mathrm{x}_{0}\right)\right\| \mathrm{d} \tau\right) \mathrm{ds}$
After a series of simplifications and using the conditions $\mathrm{C}, \mathrm{D}$ and E we have got:

$$
\begin{aligned}
& \left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \delta^{\prime}+\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{C}_{\alpha}(\mathrm{t}-\mathrm{s})^{-\alpha} \mathrm{K}_{0} \mathrm{~K}_{1} \mathrm{ds} \\
& +\quad \int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{C}_{\alpha}(\mathrm{t}-\mathrm{s})^{-\alpha} \mathrm{L}_{0}\left\|\mathrm{~A}^{-\alpha} \mathrm{x}_{w}(\mathrm{~s})-\mathrm{x}_{0}\right\|_{\alpha} \mathrm{ds} \\
& + \\
& \int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{C}_{\alpha}(\mathrm{t}-\mathrm{s})^{-\alpha} \mathrm{h}_{\mathrm{t}_{1}} \mathrm{~L}_{0}\left\|\mathrm{~A}^{-\alpha} \mathrm{x}_{w}(\mathrm{~s})-\mathrm{x}_{0}\right\|_{\alpha} \mathrm{ds} \\
& \int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{C}_{\alpha}(\mathrm{t}-\mathrm{s})^{-\alpha}\left[\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right] \mathrm{ds}
\end{aligned}
$$

By using the properties $\|x\|_{\alpha}=\left\|A^{\alpha}\right\|_{X}$, we get:
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{X}_{0}\right\|_{\mathrm{x}} \leq \delta^{\prime}+{ }_{\alpha} \mathrm{K}_{0} \mathrm{~K}_{1}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}$
$+\delta \mathrm{C}_{\alpha} \mathrm{L}_{0}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}+\delta \mathrm{C}_{\alpha} \mathrm{L}_{1} \mathrm{~h}_{\mathrm{t}_{1}}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}+$
$\left(B_{1}+h_{t_{1}} B_{2}\right) C_{\alpha}(1-\alpha)^{-1} t_{1}{ }^{1-\alpha}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \delta^{\prime}+$
$\left[\mathrm{K}_{0} \mathrm{~K}_{1}+\delta \mathrm{L}_{0}+\delta \mathrm{L}_{1} \mathrm{~h}_{\mathrm{t}_{1}}+\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right)\right]$
$\mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}\right)(\mathrm{t})-\mathrm{A}^{\alpha} \mathrm{x}_{0}\right\|_{\mathrm{x}} \leq \delta^{\prime}+\left[\mathrm{K}_{0} \mathrm{~K}_{1}+\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)\right.$
$\left.+h_{t_{1}}\left(\delta L_{0}+B_{2}\right)\right] C_{\alpha}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}$
By using condition (H.i), we get: $\|\left(\mathrm{F}_{w} \mathrm{x}_{w}\right)(\mathrm{t})$ $A^{\alpha} x_{0} \|_{x} \leq \delta$, for $0 \leq t \leq t_{1}$.

So one can select $\mathrm{t}_{1}>0$, such that:

$$
\begin{aligned}
\mathrm{t}_{1}= & \min \left\{\mathrm{t}^{\prime}, \mathrm{t}^{\prime \prime}, \mathrm{t}^{\prime \prime \prime}, \mathrm{r},\right. \\
& {\left[\left\{\mathrm{K}_{0} \mathrm{~K}_{1}+\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)+\mathrm{h}_{\mathrm{t}_{1}}\left(\delta \mathrm{~L}_{1}+\mathrm{B}_{2}\right)\right]^{-1} \mathrm{C}_{\alpha}^{-1}(1-\alpha)\right.} \\
& \left.\left.\left(\delta-\delta^{\prime}\right)\right\}^{\frac{1}{1-\alpha}}\right\}
\end{aligned}
$$

Thus, we have that $\mathrm{F}_{w}: \mathrm{S}_{w} \longrightarrow \mathrm{~S}_{w}$
Now, to show that $\mathrm{F}_{w}$ is a strict contraction on $\mathrm{S}_{w}$, this will ensure the existence of a unique $S$-classical solution to the semilinear initial value control problem. *
Let $\mathrm{X}_{w}^{\prime}, \mathrm{X}_{w}^{\prime \prime} \in \mathrm{S}_{w}$, then:
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}}=\| \mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{x}_{0}+$ $\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})(\mathrm{B} w)(\mathrm{s}) \mathrm{ds}+$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left[f\left(s, A^{-\alpha} x_{w}^{\prime \prime}(s)\right)\right.$
$\left.\int_{s=0}^{t} h(s-\tau) g\left(\tau, A^{-\alpha} x_{w}^{\prime \prime}(\tau)\right) d \tau\right] d s-S(t) A^{\alpha} x_{0}$
$-\int_{s=0}^{t} \mathrm{~A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})(\mathrm{B} w)(\mathrm{s}) \mathrm{ds}-$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left[f\left(s, A^{-\alpha} x_{w}^{\prime}(s)\right)\right.$
$+\quad \int_{s=0}^{t} h(s-\tau) g\left(\tau, A^{-\alpha} x_{w}^{\prime}(\tau)\right) d \tau d s \|_{x}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}}=$
$\| \int_{s=0}^{t} A^{\alpha} S(t-s)\left[f\left(s, A^{-\alpha} x_{w}^{\prime \prime}(s)\right)+\int_{s=0}^{t} h(s-\tau) g\left(\tau, A^{-\alpha} x_{w}^{\prime \prime}(\tau)\right) d \tau\right] d s$
$-\int_{s=0}^{t} A^{\alpha} S(t-s)\left[f\left(s, A^{-\alpha} x_{w}^{\prime}(s)\right)+\int_{s=0}^{t} h(s-\tau) g\left(\tau, A^{-\alpha} x_{w}^{\prime}(\tau)\right) d \tau\right] d s \|_{x}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t}) \quad-\quad\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq$
$\int_{\mathrm{s}=0}^{\mathrm{t}}\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\right\|\left\|\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{x}_{w}^{\prime \prime}(\mathrm{s})\right)-\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{x}_{w}^{\prime}(\mathrm{s})\right)\right\|_{\mathrm{X}} \mathrm{ds}+$
$\int_{s=0}^{t}\left\|A^{\alpha} S(t-s)\right\|\left[\int_{s=0}^{t}|h(s-\tau)|\left\|g\left(\tau, A^{-\alpha} x_{w}^{\prime \prime}(\tau)\right)-g\left(\tau, A^{-\alpha} x_{w}^{\prime}(\tau)\right)\right\| d \tau\right] d s$
By using the condition $C$ and the properties
$\left\|A^{\alpha} S(t)\right\| \leq C_{\alpha} t^{-\alpha}$ with $\quad h_{r}=\int_{0}^{r}|h(s)| d s$,
We have got:
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq$
$\int_{s=0}^{\mathrm{t}} \mathrm{C}_{\alpha}(\mathrm{t}-\mathrm{s})^{-\alpha} \mathrm{L}_{0}\left\|\mathrm{~A}^{-\alpha} \mathrm{x}_{w}^{\prime \prime}(\mathrm{s})-\mathrm{A}^{-\alpha} \mathrm{x}_{w}^{\prime}(\mathrm{s})\right\| \mathrm{ds}+$
$\int_{s=0}^{t} C_{\alpha}(t-s)^{-\alpha} h_{h_{1}} L_{1}\left\|A^{-\alpha} x_{w}^{\prime \prime}(\tau)-A^{-\alpha} x_{w}^{\prime}(\tau)\right\| d s$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{~L}_{0}$ $\left\|\mathrm{x}_{w}^{\prime \prime}(\mathrm{s})-\mathrm{x}_{w}^{\prime}(\mathrm{s})\right\|_{\mathrm{X}} \mathrm{t}_{1}{ }^{1-\alpha}+\mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{~h}_{\mathrm{t}_{1}} \mathrm{~L}_{0}$
$\left\|x_{w}^{\prime \prime \prime}(\tau)-x_{w}^{\prime}(\tau)\right\|_{x} t_{1}{ }^{1-\alpha}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{~L}_{0}$
$\sup _{0 \leq \mathrm{t} \mathrm{t}_{1}}\left\|\mathrm{x}_{w}^{\prime \prime}(\mathrm{t})-\mathrm{x}_{w}^{\prime}(\mathrm{t})\right\|_{\mathrm{X}} \mathrm{t}_{1}{ }^{1-\alpha} \quad+\quad \mathrm{C}_{\alpha}(1-\alpha)^{-1}$
$\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~L}_{1} \sup _{0 \leq \mathrm{t} \leq \mathrm{t}_{1}}\left\|\mathrm{x}_{w}^{\prime \prime}(\mathrm{t})-\mathrm{x}_{w}^{\prime}(\mathrm{t})\right\|_{\mathrm{X}} \mathrm{t}_{1}{ }^{1-\alpha}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{~L}_{0}$
$\left\|\mathrm{X}_{w}^{\prime \prime}-\mathrm{x}_{w}^{\prime}\right\|_{\mathrm{Y}} \quad \mathrm{t}_{1}{ }^{1-\alpha}+\mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{~h}_{\mathrm{t} 1} \mathrm{~L}_{1}$
$\left\|\mathrm{X}_{w}^{\prime \prime}-\mathrm{x}_{w}^{\prime}\right\|_{\mathrm{Y}} \mathrm{t}_{1}{ }^{1-\alpha}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq\left(\mathrm{L}_{0}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~L}_{1}\right)$
$\mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}\left\|\mathrm{X}_{w}^{\prime \prime}-\mathrm{X}_{w}^{\prime}\right\|_{\mathrm{Y}}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \frac{1}{\delta} \delta\left(\mathrm{~L}_{0}+\mathrm{L}_{1} \mathrm{~h}_{\mathrm{t} 1}\right)$
$\mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}\left\|\mathrm{X}_{w}^{\prime \prime}-\mathrm{X}_{w}^{\prime}\right\|_{\mathrm{Y}}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \frac{1}{\delta}\left[\delta \mathrm{~L}_{0}+\delta \mathrm{h}_{\mathrm{t} 1} \mathrm{~L}_{1}\right]$
$\mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}\left\|\mathrm{X}_{w}^{\prime \prime}-\mathrm{X}_{w}^{\prime}\right\|_{\mathrm{Y}}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \frac{1}{\delta}\left[\delta \mathrm{~L}_{0}+\delta\right.$ $\left.\mathrm{h}_{\mathrm{tl}} \mathrm{L}_{1}+\mathrm{K}_{0} \mathrm{~K}_{1}+\mathrm{B}_{1}+\mathrm{h}_{\mathrm{tl}} \mathrm{B}_{2}\right] \quad \mathrm{C}_{\alpha}(1-\alpha)^{-1} \mathrm{t}_{1}{ }^{1-\alpha}$ $\left\|\mathrm{X}_{w}^{\prime \prime}-\mathrm{X}_{w}^{\prime}\right\|_{\mathrm{Y}}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \frac{1}{\delta}\left[\mathrm{~K}_{0} \mathrm{~K}_{1}+\right.$ $\left.\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)+\mathrm{h}_{\mathrm{t} 1}\left(\delta \mathrm{~L}_{1}+\mathrm{B}_{2}\right)\right]$ $\mathrm{C}_{\alpha}(1-\alpha)^{-1}\left\|\mathrm{x}_{w}^{\prime \prime}-\mathrm{x}_{w}^{\prime}\right\|_{\mathrm{Y}} \mathrm{t}_{1}{ }^{1-\alpha}$
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq \frac{1}{\delta} \quad\left[\mathrm{~K}_{0} \mathrm{~K}_{1}+\right.$ $\left.\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)+\mathrm{h}_{\mathrm{tl}}\left(\delta \mathrm{L}_{1}+\mathrm{B}_{2}\right)\right] \mathrm{C}_{\alpha}(1-\alpha)^{-1}\left[\mathrm{~K}_{0} \mathrm{~K}_{1}+\right.$ $\left.\left(\delta \mathrm{L}_{0}+\mathrm{B}_{1}\right)+\mathrm{h}_{\mathrm{t} 1}\left(\delta \mathrm{~L}_{1}+\mathrm{B}_{2}\right)\right]^{-1} \mathrm{C}_{\alpha}^{-1}(1-\alpha)\left(\delta-\delta^{\prime}\right)$ $\left\|x_{w}^{\prime \prime}-x_{w}^{\prime}\right\|_{Y}\{$ by the condition (H.i) $\}$.
$\left\|\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq\left(1-\frac{\delta^{\prime}}{\delta}\right)\left\|\mathrm{x}_{w}^{\prime \prime}-\mathrm{x}_{w}^{\prime}\right\|_{\mathrm{Y}}$

Taking the supremum over $\left[0, t_{1}\right]$ of both sides to (7), we have got:
$\sup _{0 \leq \leq \mathrm{t}_{1}}\left\|\left(\mathrm{~F}_{w} \mathrm{X}_{w}^{\prime \prime}\right)(\mathrm{t})-\left(\mathrm{F}_{w} \mathrm{x}_{w}^{\prime}\right)(\mathrm{t})\right\|_{\mathrm{x}} \leq\left(1-\frac{\delta^{\prime}}{\delta}\right)$ $\left\|\mathrm{x}_{w}^{\prime \prime}-\mathrm{x}_{w}^{\prime}\right\|_{\mathrm{Y}}$
$\left\|\mathrm{F}_{w} \mathrm{X}_{w}^{\prime \prime}-\mathrm{F}_{w} \mathrm{X}_{w}^{\prime}\right\|_{\mathrm{x}} \leq\left(1-\frac{\delta^{\prime}}{\delta}\right)\left\|\mathrm{x}_{w}^{\prime \prime}-\mathrm{x}_{w}^{\prime}\right\|_{\mathrm{Y}},\{$ by $\left.\|y\|_{\mathrm{Y}}=\sup _{0 \leq \leq \leq t_{1}}\|y(t)\|_{\mathrm{x}}\right\}$

Thus, $\mathrm{F}_{w}$ is a strict contraction map from $\mathrm{S}_{w}$ into $\mathrm{S}_{w}$ and therefore by the Banach contraction principle there exist a unique fixed point $\mathrm{X}_{w}$ of $\mathrm{F}_{w}$ in $\mathrm{S}_{w}$, i.e., there is a unique $\mathrm{x}_{w} \in \mathrm{~S}_{w}$, such that $\mathrm{F}_{w} \mathrm{x}_{w}=\mathrm{x}_{w}$. This fixed point satisfies the integral equation:
$x_{w}(t)=S(t) A^{\alpha} x_{0}+\int_{s=0}^{t} A^{\alpha} S(t-s)\left[f\left(s, A^{-\alpha} x_{w}(s)\right)+\right.$
$\left.\int_{\tau=0}^{s} h(s-\tau) g\left(\tau, A^{-\alpha} x_{w}(\tau)\right) d \tau\right] d s$
$+\int_{s=0}^{t} A^{\alpha} S(t-s) B w(s) d s$, for $0 \leq t \leq t_{1}, \quad \forall$
$w(.) \in L^{p}\left(\left(0, t_{1}\right): O\right) \ldots \ldots . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~(8) ~$
For simplification, we set $\tilde{\mathrm{f}}(\mathrm{t})=\mathrm{f}\left(\mathrm{t}, \mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{t})\right)$, $\tilde{g}(t)=g\left(t, A^{-\alpha} x_{w}(t)\right)$. Then equation (8) can be rewritten as:
$\mathrm{X}_{w}(\mathrm{t})=\mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{x}_{0}+$
$\left.\int_{s=0}^{t} A^{\alpha} S(t-s)\left[\tilde{f}(s)+\int_{\tau=0}^{s} h(s-\tau) \tilde{g}(\tau)\right) d \tau\right] d s+$
$\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s}) \mathrm{B} w(\mathrm{~s}) \mathrm{ds}$, for $0 \leq \mathrm{t} \leq \mathrm{t}_{1}$,
$\forall w(.) \in \mathrm{L}^{\mathrm{p}}\left(\left(0, \mathrm{t}_{1}\right): \mathrm{O}\right)$
To show that $\tilde{f}(\mathrm{t})$ is locally Hölder continuous on ( $0, \mathrm{t}_{1}$ ].

We first show that $\mathrm{X}_{w}(\mathrm{t})$ given by (9) is locally Hölder continuous on $\left(0, t_{1}\right]$.

Notice that, from the theorem (IV.7) in [4], it follows that for every $0<\beta<1-\alpha$ and every $0<\mathrm{h}<1$, we have:
$\left\|(S(h)-I) A^{\alpha} S(t-s)\right\| \leq C_{\beta} h^{\beta}\left\|A^{\alpha+\beta} S(t-s)\right\|$ $\leq \mathrm{Ch}^{\beta}(\mathrm{t}-\mathrm{s})^{-(\alpha+\beta)}$.

Which is useful for proving $\mathrm{x}_{w}(\mathrm{t})$ given by (9) is locally Hölder continuous on ( $0, \mathrm{t}_{1}$ ].

Next, we have for $0<t<t+h \leq t_{1}$
$\left\|\mathrm{x}_{w}(\mathrm{t}+\mathrm{h})-\mathrm{x}_{w}(\mathrm{t})\right\|_{\mathrm{x}}=\| \mathrm{S}(\mathrm{t}+\mathrm{h}) \mathrm{A}^{\alpha} \mathrm{x}_{0}+$ $\int_{s=0}^{t+h} A^{\alpha} S(t+h-s)\left[\tilde{f}(s)+\int_{\tau=0}^{s} h(s-\tau) \tilde{g}(\tau) d \tau\right] d s+$
$\int_{s=0}^{\mathrm{t}+\mathrm{h}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}+\mathrm{h}-\mathrm{s}) \mathrm{B} w(\mathrm{~s}) \mathrm{ds}-\mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{X}_{0}-$
$\int_{s=0}^{t+h} A^{\alpha} S(t-s)\left[\tilde{f}(s)+\int_{\tau=0}^{s} h(s-\tau) \tilde{g}(\tau) d \tau\right] d s-$
$\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s}) \mathrm{B} w(\mathrm{~s}) \mathrm{ds} \|_{\mathrm{x}}$
$\left\|\mathrm{x}_{w}(\mathrm{t}+\mathrm{h})-\mathrm{x}_{w}(\mathrm{t})\right\|_{\mathrm{x}}=\| \mathrm{S}(\mathrm{t}+\mathrm{h}) \mathrm{A}^{\alpha} \mathrm{x}_{0}-\mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{x}_{0}+$
$\int_{s=0}^{t} A^{\alpha} S(t+h-s)\left[\tilde{f}(s)+\int_{\tau=0}^{s} h(s-\tau) \tilde{g}(\tau) d \tau\right] d s+$
$\int_{s=t}^{t+h} A^{\alpha} S(t+h-s)\left[\tilde{f}(s)+\int_{\tau=0}^{s} h(s-\tau) \tilde{g}(\tau) d \tau d s+\right.$
$\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}+\mathrm{h}-\mathrm{s}) \mathrm{B} w(\mathrm{~s}) \mathrm{ds}+$
$\int_{\mathrm{s}=\mathrm{t}}^{\mathrm{t}+\mathrm{h}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}+\mathrm{h}-\mathrm{s}) \mathrm{B} w(\mathrm{~s}) \mathrm{ds}-$
$\int_{s=0}^{t} A^{\alpha} S(t-s)\left[\tilde{f}(s)+\int_{\tau=0}^{s} h(s-\tau) \tilde{g}(\tau) d \tau\right] d s-$
$\int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s}) \mathrm{B} w(\mathrm{~s}) \mathrm{ds} \|_{\mathrm{x}}$

$$
\begin{align*}
& \left\|\mathrm{x}_{w}(\mathrm{t}+\mathrm{h})-\mathrm{x}_{w}(\mathrm{t})\right\|_{\mathrm{x}} \leq\left\|(\mathrm{S}(\mathrm{~h})-\mathrm{I}) \mathrm{S}(\mathrm{t}) \mathrm{A}^{\alpha} \mathrm{u}_{0}\right\|_{\mathrm{x}}+ \\
& \int_{s=0}^{t} \|(S(h)-I) A^{\alpha} S(t-s)\left[\|\tilde{f}(s)\|_{X}+\int_{\tau=0}^{s}|h(s-\tau)|\|\tilde{g}(\tau)\|_{X} d \tau\right] d s \\
& +\int_{\mathrm{s}=0}^{\mathrm{t}}\left\|(\mathrm{~S}(\mathrm{~h})-\mathrm{I}) \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\right\|_{\mathrm{X}}\|\mathrm{~B} w(\mathrm{~s})\|_{\mathrm{X}} \mathrm{ds}+ \\
& \int_{s=t}^{t+h}\left\|A^{\alpha} S(t+h-s)\right\|_{X}\left[\|\tilde{f}(s)\|_{X}+\int_{\tau=0}^{s}|h(s-\tau)|\|\tilde{g}(\tau)\|_{X} d \tau\right] d s \\
& +\int_{\mathrm{s}=\mathrm{t}}^{\mathrm{t}+\mathrm{h}}\left\|\mathrm{~A}^{\alpha} \mathrm{S}(\mathrm{t}+\mathrm{h}-\mathrm{s})\right\|_{\mathrm{X}}\|\mathrm{~B} w(\mathrm{~s})\|_{\mathrm{X}} \mathrm{ds} \\
& =\mathrm{I}_{1}+\mathrm{I}_{2}+\mathrm{I}_{3}+\mathrm{I}_{4}+\mathrm{I}_{5} . \tag{11}
\end{align*}
$$

We estimate each of the terms of (11) separately.
$\left.I_{1}=\| S(h)-I\right) S(t) A^{\alpha} x_{0}\left\|_{x} \leq C_{\beta} h^{\beta}\right\| A^{\alpha+\beta} S(t) \|_{X}$ $\left\|\mathrm{x}_{0}\right\| \leq \mathrm{Ch}^{\beta}\left\|\mathrm{x}_{0}\right\| \mathrm{t}^{-(\alpha+\beta)}$ \{by using equation 10$\}$
$\mathrm{I}_{1} \leq \mathrm{M}_{1} \mathrm{~h}^{\beta}$, where $\mathrm{M}_{1}=\mathrm{C}\left\|\mathrm{x}_{0}\right\| \mathrm{t}^{-(\alpha+\beta)}$ depends on $t$ for $0 \leq t \leq t_{1}$.
$\mathrm{I}_{2}$
$\int_{s=0}^{t} \|(S(h)-I) A^{\alpha} S(t-s)\left[\|\tilde{f}(s)\|_{X}+\int_{\tau=0}^{s}|h(s-\tau)|\|\tilde{g}(\tau)\|_{X} d \tau\right] d s$
$\mathrm{I}_{2} \leq \int_{\mathrm{s}=0}^{\mathrm{t}}\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right) \mathrm{Ch}^{\beta}(\mathrm{t}-\mathrm{s})^{-(\alpha+\beta)} \mathrm{ds} \leq$
$\left(B_{1}+h_{t_{1}} B_{2}\right) \mathrm{Ch}^{\beta} \int_{\mathrm{s}=0}^{\mathrm{t}}(\mathrm{t}-\mathrm{s})^{-(\alpha+\beta)} \mathrm{ds}$,
\{by using equation (10) and the condition $D$ with

$$
\begin{aligned}
& \left.\mathrm{h}_{\mathrm{r}}=\int_{0}^{\mathrm{r}}|\mathrm{~h}(\mathrm{~s})| \mathrm{ds}\right\} \\
& \mathrm{I}_{2} \leq \frac{\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right) \mathrm{Ch}^{\beta}}{1-(\alpha+\beta)} \mathrm{t}^{-(\alpha+\beta)+1} \leq \\
& \frac{\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right) \mathrm{Ch}^{\beta}}{1-(\alpha+\beta)} \mathrm{t}_{1}^{-(\alpha+\beta)+1}
\end{aligned}
$$

$I_{2} \leq M_{2} h^{\beta}$, where $M_{2}=\frac{\left(B_{1}+h_{t_{1}} B_{2}\right) \text { Ch }^{\beta} \mathrm{t}_{1}^{-(\alpha+\beta)+1}}{1-(\alpha+\beta)}$ is independent of $t$ for $0 \leq t \leq t_{1}$.
$\mathrm{I}_{3}=\int_{\mathrm{s}=0}^{\mathrm{t}}\left\|(\mathrm{S}(\mathrm{h})-\mathrm{I}) \mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}-\mathrm{s})\right\|_{\mathrm{X}}\|\mathrm{B} w(\mathrm{~s})\|_{\mathrm{X}} \mathrm{ds}$
$\mathrm{I}_{3} \leq \int_{\mathrm{s}=0}^{\mathrm{t}} \mathrm{Ch}^{\beta}(\mathrm{t}-\mathrm{s})^{-(\alpha+\beta)} \mathrm{K}_{0} \mathrm{~K}_{1} \mathrm{ds} \leq$
$\mathrm{Ch}^{\beta} \mathrm{K}_{0} \mathrm{~K}_{1} \int_{\mathrm{s}=0}^{\mathrm{t}}(\mathrm{t}-\mathrm{s})^{-(\alpha+\beta)} \mathrm{ds}$
\{by using equation (10) and the condition G$\}$,
$\mathrm{I}_{3} \leq \frac{\mathrm{Ch}^{\beta} \mathrm{K}_{0} \mathrm{~K}_{1}}{1-(\alpha+\beta)} \mathrm{t}^{1-(\alpha+\beta)} \leq \frac{\mathrm{Ch}^{\beta} \mathrm{K}_{0} \mathrm{~K}_{1}}{1-(\alpha+\beta)} \mathrm{t}_{1}^{1-(\alpha+\beta)}$
$\mathrm{I}_{3} \leq \mathrm{M}_{3} h^{\beta}$, where $\mathrm{M}_{3}=\frac{\mathrm{Ch}^{\beta} \mathrm{K}_{0} \mathrm{~K}_{1} 1_{1}^{1-(\alpha+\beta)}}{1-(\alpha+\beta)}$ is independent of $t$ for $0 \leq t \leq t_{1}$.
$\mathrm{I}_{4}=\int_{\mathrm{s}=\mathrm{t}}^{\mathrm{t}+\mathrm{h}}\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}+\mathrm{h}-\mathrm{s})\right\|_{\mathrm{X}}\left[\|\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}}+\int_{\tau=0}^{\mathrm{s}}|\mathrm{h}(\mathrm{s}-\tau)|\|\tilde{\mathrm{g}}(\tau)\|_{\mathrm{X}} \mathrm{d} \mathrm{\tau}\right] \mathrm{ds}$
$\mathrm{I}_{4} \leq\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right) \mathrm{C}_{\alpha} \int_{\mathrm{s}=\mathrm{t}}^{\mathrm{t}+\mathrm{h}}(\mathrm{t}+\mathrm{h}-\mathrm{s})^{-\alpha} \mathrm{ds} \leq$
$\frac{\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right) \mathrm{C}_{\alpha}}{1-\alpha} \mathrm{h}^{1-\alpha}$ \{by using the condition D and the properties $\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t})\right\| \leq \mathrm{C}_{\alpha} \mathrm{t}^{-\alpha}$ with $\left.\mathrm{h}_{\mathrm{r}}=\int_{0}^{\mathrm{r}}|\mathrm{h}(\mathrm{s})| \mathrm{ds}\right\}$,
$\mathrm{I}_{4} \leq \mathrm{M}_{4} \mathrm{~h}^{1-\alpha}$, where $\mathrm{M}_{4}=\frac{\left(\mathrm{B}_{1}+\mathrm{h}_{\mathrm{t}_{1}} \mathrm{~B}_{2}\right) \mathrm{C}_{\alpha}}{1-\alpha}$ is independent of $t$ for $0 \leq t \leq t_{1}$,
So that $\mathrm{I}_{4} \leq \mathrm{M}_{4} \mathrm{~h}^{\beta}$.
$\mathrm{I}_{5}=\int_{\mathrm{s}=\mathrm{t}}^{\mathrm{t} \mathrm{h}}\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t}+\mathrm{h}-\mathrm{s})\right\|_{\mathrm{X}}\|\mathrm{B} w(\mathrm{~s})\|_{\mathrm{X}} \mathrm{ds}$
$\mathrm{I}_{5} \leq \mathrm{C}_{\alpha} \mathrm{K}_{0} \mathrm{~K}_{1} \int_{\mathrm{s}=\mathrm{t}}^{\mathrm{t}+\mathrm{h}}(\mathrm{t}+\mathrm{h}-\mathrm{s})^{-\alpha} \mathrm{ds} \leq \frac{\mathrm{C}_{\alpha} \mathrm{K}_{0} \mathrm{~K}_{1}}{1-\alpha} \mathrm{h}^{1-\alpha}$,
\{by using the condition $G$ and the properties $\left.\left\|\mathrm{A}^{\alpha} \mathrm{S}(\mathrm{t})\right\| \leq \mathrm{C}_{\alpha} \mathrm{t}^{-\alpha}\right\}$,
$\mathrm{I}_{5} \leq \mathrm{M}_{5} \mathrm{~h}^{1-\alpha}$, where $\mathrm{M}_{5}=\frac{\mathrm{C}_{\alpha} \mathrm{K}_{0} \mathrm{~K}_{1}}{1-\alpha}$ is independent of $t \in\left[0, t_{1}\right]$, so that $I_{5} \leq M_{5} h^{\beta}$.
Combining (11) with these estimates, it follows that there is a constant $\mathrm{C}_{1}$ such that:
$\left\|\mathrm{x}_{w}(\mathrm{t}+\mathrm{h})-\mathrm{x}_{w}(\mathrm{t})\right\|_{\mathrm{x}} \leq \mathrm{C}_{1} \mathrm{~h}^{\beta} \leq \mathrm{C}_{1}\left|\mathrm{~h}^{\beta}\right|$
Where $\mathrm{C}_{1}=\mathrm{M}_{1}+\mathrm{M}_{2}+\mathrm{M}_{3}+\mathrm{M}_{4}+\mathrm{M}_{5}$.
$\Rightarrow$ Let $\mathrm{k}=\mathrm{t}+\mathrm{h} \Rightarrow \mathrm{h}=\mathrm{k}-\mathrm{t}$
$\Rightarrow\left\|\mathrm{x}_{w}(\mathrm{k})-\mathrm{x}_{w}(\mathrm{t})\right\|_{\mathrm{x}} \leq \mathrm{C}_{1}|\mathrm{k}-\mathrm{t}|^{\beta}$. For $0<\mathrm{t}<\mathrm{k} \leq \mathrm{t}_{1}$.

Therefore $\mathrm{x}_{w}$ is locally Hölder continuous on $\left(0, t_{1}\right]$.
Now, to show that $\tilde{f}(t)$ is locally Hölder continuous on ( $0, \mathrm{t}_{1}$ ], we have, For $\mathrm{t}>\mathrm{s}$ :
$\|\tilde{\mathrm{f}}(\mathrm{t})-\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}}=\| \mathrm{f}\left(\mathrm{t}, \mathrm{A}^{-\alpha} \mathrm{x}_{w}(\mathrm{t})\right)-\mathrm{f}(\mathrm{s}$, $\left.\mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{~s})\right) \|_{\mathrm{x}}$
$\|\tilde{\mathrm{f}}(\mathrm{t})-\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}} \leq \mathrm{L}_{0}\left[|\mathrm{t}-\mathrm{s}|^{\theta}+\left\|\mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{t})-\mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{~s})\right\|_{\alpha}\right]$ for $0<\theta \leq 1$ \{by using the condition C$\}$,
$\|\tilde{\mathrm{f}}(\mathrm{t})-\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}} \leq \mathrm{L}_{0}\left[|\mathrm{t}-\mathrm{s}|^{\theta}+\left\|\mathrm{x}_{w}(\mathrm{t})-\mathrm{x}_{w}(\mathrm{~s})\right\|_{\mathrm{x}}\right]$
\{by using the properties $\left.\|\mathrm{x}\|_{\alpha}=\left\|\mathrm{A}^{\alpha} \mathrm{x}\right\|_{\mathrm{x}}\right\}$,
$\|\tilde{f}(t)-\tilde{f}(s)\|_{x} \leq L_{0}\left[|t-s|^{\theta}+C_{1}|t-s|^{\beta}\right],\{$ by using equation (12) \}
$\|\tilde{f}(t)-\tilde{f}(s)\|_{\mathrm{X}} \leq \mathrm{L}_{0}\left[|\mathrm{t}-\mathrm{s}|^{\gamma}+\mathrm{C}_{1}|\mathrm{t}-\mathrm{s}|^{\gamma}\right]$, where $\gamma$
$=\min \{\theta, \beta\}$
$\|\tilde{\mathrm{f}}(\mathrm{t})-\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}} \leq \mathrm{L}_{0}\left(1+\mathrm{C}_{1}\right)|\mathrm{t}-\mathrm{s}|^{\gamma}$
$\|\tilde{\mathrm{f}}(\mathrm{t})-\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}} \leq \mathrm{C}_{2}|\mathrm{t}-\mathrm{s}|^{\gamma}$,
Where $\mathrm{C}_{2}=\mathrm{L}_{0}\left(1+\mathrm{C}_{1}\right)$ is a positive constant.
Let $\tilde{\mathrm{h}}(\mathrm{t})=\tilde{\mathrm{f}}(\mathrm{t})+\int_{\tau=0}^{\mathrm{t}} \mathrm{h}(\mathrm{t}-\tau) \tilde{\mathrm{g}}(\tau) \mathrm{d} \tau+\mathrm{B} w(\mathrm{t})$
To show that $\tilde{\mathrm{h}}(\mathrm{t})$ is locally Hölder continuous on ( $0, \mathrm{t}_{1}$ ]. For $\mathrm{t}>\mathrm{s}$, we have:
$\|\tilde{h}(t)-\tilde{h}(s)\|_{X}=$
$\| \tilde{\mathrm{f}}(\mathrm{t})+\int_{\tau=0}^{\mathrm{t}} \mathrm{h}(\mathrm{t}-\tau) \tilde{\mathrm{g}}(\tau) \mathrm{d} \tau-\tilde{\mathrm{f}}(\mathrm{s})-\int_{\tau=0}^{\mathrm{s}} \mathrm{h}(\mathrm{s}-\tau) \tilde{\mathrm{g}}(\tau) \mathrm{d} \tau$
$+\mathrm{B} w(\mathrm{t})-\mathrm{B} w(\mathrm{~s}) \|_{\mathrm{x}}$
$\|\tilde{h}(t)-\tilde{h}(\mathrm{~s})\|_{\mathrm{X}} \leq\|\tilde{\mathrm{f}}(\mathrm{t})-\tilde{\mathrm{f}}(\mathrm{s})\|_{\mathrm{X}}+$
$\int_{\tau=0}^{t}|\mathrm{~h}(\mathrm{t}-\tau)-\mathrm{h}(\mathrm{s}-\tau)|| | \tilde{\mathrm{g}}(\tau) \|_{\mathrm{X}} \mathrm{d} \tau+$
$\|\mathrm{B}(w(\mathrm{t})-w(\mathrm{~s}))\|_{\mathrm{X}}$
After a series of simplifications and using the conditions I, D and J with equation (13), we have got:
$\|\tilde{\mathrm{h}}(\mathrm{t})-\tilde{\mathrm{h}}(\mathrm{s})\|_{\mathrm{X}} \leq \mathrm{C}_{2}|\mathrm{t}-\mathrm{s}|^{\gamma}+\mathrm{C}_{3} \mathrm{~B}_{2}|\mathrm{t}-\mathrm{s}|^{9} \mathrm{t}_{1}+$ $K_{0} \mathrm{R}_{0}|\mathrm{t}-\mathrm{s}|^{\mathrm{s}}$
$\|\tilde{h}(t)-\tilde{h}(s)\|_{X} \leq C_{2}|t-s|^{\wp}+C_{3} B_{2}|t-s|^{\infty} t_{1}+$ $\mathrm{K}_{0} \mathrm{R}_{0} \| \mathrm{t}-\left.\mathrm{s}\right|^{\varsigma}$, where $\wp=\min \{\gamma, \vartheta, \xi\}$
$\|\tilde{\mathrm{h}}(\mathrm{t})-\tilde{\mathrm{h}}(\mathrm{s})\|_{\mathrm{X}} \leq\left\{\mathrm{C}_{2}+\mathrm{C}_{3} \mathrm{~B}_{2} \mathrm{t}_{1}+\mathrm{K}_{0} \mathrm{R}_{0}\right\} \mid \mathrm{t}-$ $\mathrm{s}^{\mathfrak{\beta}}$ 。
This show that $\tilde{\mathrm{h}}(\mathrm{t})$ is locally Hölder continuous on $\left(0, t_{1}\right]$.

From the theorem (2.4.1) in [5], we infer that the function:
$\mathrm{v}_{w}(\mathrm{t})=\mathrm{S}(\mathrm{t}) \mathrm{X}_{0}+\int_{0}^{\mathrm{t}} \mathrm{S}(\mathrm{t}-\mathrm{s}) \tilde{\mathrm{h}}(\mathrm{s}) \mathrm{ds}$, where
$\tilde{\mathrm{h}}(\mathrm{t})=\tilde{\mathrm{f}}(\mathrm{t})+\int_{\tau=0}^{\mathrm{t}} \mathrm{h}(\mathrm{t}-\tau) \tilde{\mathrm{g}}(\tau) \mathrm{d} \tau+\mathrm{B} w(\mathrm{t})$.
$\mathrm{v}_{\mathrm{w}}(\mathrm{t})=\mathrm{S}(\mathrm{t}) \mathrm{x}_{0}+$
$\int_{0}^{\mathrm{t}} \mathrm{S}(\mathrm{t}-\mathrm{s})\left[\tilde{\mathrm{f}}(\mathrm{s})+\int_{\tau=0}^{\mathrm{s}} \tilde{\mathrm{h}}(\mathrm{s}-\tau) \tilde{\mathrm{g}}(\tau) \mathrm{d} \tau+\mathrm{B} w(\mathrm{~s})\right] \mathrm{ds}$
$\mathrm{v}_{w}(\mathrm{t})=\mathrm{S}(\mathrm{t}) \mathrm{x}_{0}+$
$\int_{0}^{t} \mathrm{~S}(\mathrm{t}-\mathrm{s})\left[\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{~s})\right)+\int_{\tau=0}^{\mathrm{s}} \mathrm{h}(\mathrm{s}-\tau) \tilde{\mathrm{g}}\left(\tau, \mathrm{A}^{-\alpha} \mathrm{X}_{w}(\tau)\right) \mathrm{d} \tau\right.$
$+\mathrm{B} w(\mathrm{~s})] \mathrm{ds}$.
For $0<\mathrm{t} \leq \mathrm{t}_{1}, \forall w \in \mathrm{~L}^{\mathrm{p}}\left(\left(0, \mathrm{t}_{1}\right]: \mathrm{O}\right)$.
is $X_{a}$-valued, that the integral terms in (14) are functions in $C^{1}\left(\left(0, t_{1}\right]: X\right)$ and that $\mathrm{v}_{w}(\mathrm{t}) \in \mathrm{D}(\mathrm{A}), \forall \mathrm{t} \in\left(0, \mathrm{t}_{1}\right]$. Operating on both sides of equation (14) with $\mathrm{A}^{\alpha}$, we have got:
$A^{\alpha} v_{w}(t)=S(t) A^{\alpha} x_{0}+$
$\int_{0}^{t} \mathrm{~S}(\mathrm{t}-\mathrm{s}) \mathrm{A}^{\alpha}\left[\mathrm{f}\left(\mathrm{s}, \mathrm{A}^{-\alpha} \mathrm{X}_{w}(\mathrm{~s})\right)+\int_{\tau=0}^{\mathrm{s}} \mathrm{h}(\mathrm{s}-\tau)\right.$
$\left.\tilde{\mathbf{g}}\left(\tau, \mathrm{A}^{-\alpha} \mathrm{X}_{w}(\tau)\right) \mathrm{d} \tau+\mathrm{B} w(\mathrm{~s})\right] \mathrm{ds}$
From equation (8), implies that $A^{\alpha} v_{w}(t)=$ $\mathrm{X}_{w}(\mathrm{t})$, i.e., $\mathrm{v}_{w}(\mathrm{t})=\mathrm{A}^{-\alpha} \mathrm{x}_{w}(\mathrm{t})$,

For $0<\mathrm{t} \leq \mathrm{t}_{1}, \forall w(.) \in \mathrm{L}^{\mathrm{p}}\left(\left(0, \mathrm{t}_{1}\right]: \mathrm{O}\right)$, and hence that $v_{w}(t)$ is a $C^{1}$ function on $\left[0, t_{1}\right]$. So we have got a unique S-classical solution $\mathrm{v}_{\mathrm{w}} \in \mathrm{C}\left(\left[0, \mathrm{t}_{1}\right]: \mathrm{X}\right)$.

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